# In fMRI a Dual Echo Time<br/>EPI Pulse SequenceCOLLEGE<br/>OF WISCONSINEPI Pulse SequenceCan Induce Sources of Error in<br/>Dynamic Magnetic Field Maps

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### Introduction

- Fast imaging sequences such as Echo Planar Imaging (EPI) expose imperfections in the magnetic environment
  - Long exposure, often 50, 60, 70+ milliseconds of nearcontinuous readout
  - Long delay between adjacent k-space points;
- Results of EPI acquisitions are generally the target for optimization due to
  - Low SNR
  - Artifact prone
  - Common target for statistical analysis (fMRI)

#### Introduction

• B<sub>0</sub> field off-resonance

(resonance frequency offset)

- Caused by spatially varying magnetic susceptibility
- Phase accrues over the readout time, leading to warping in the transformed image
- Difficult to register functional data to anatomical volumes
- Usually considered temporally invariant

# **Dynamic Implications**

- In reality, variation occurs during a series of EPI data, such as in fMRI<sup>1,2</sup>
  - Leads to variable warping, potentially confounding motion correction
  - variable phase accrual, thus increased temporal phase variance
  - Serious confound to complex-valued statistical analysis<sup>1</sup>

<sup>1</sup>AD Hahn et al., NIMG 44:742-52, 2009 <sup>2</sup>PF Van de Moortele et al.: MRM 47:888-895, 2002.

# **Dual Echo Time EPI**

• Resonance offset estimated from phase difference between images with different *TE*<sup>2</sup>

• Alternate *TE* over an entire series, as in Hutton, et. al<sup>1</sup>, for Dynamic estimation

$$\Delta \hat{\omega}_{t} = \frac{\arg\left(e^{i\hat{\phi}}e^{-i\hat{\phi}_{-1}}\right)}{TE_{t} - TE_{t-1}}$$

 $\Delta \hat{\omega}_t$  = estimated frequency offset at time *t*  $\hat{\phi}_t$  = estimated phase at time *t* t = 1, ..., N - 1

<sup>1</sup>C Hutton et al., NIMG 16:217-240, 2002 <sup>2</sup>PJ Reber et al., MRM 39:328-330, 1998

# **Dual Echo Time EPI**

- Suffers from logical flaw as a dynamic method
  - Formula for field offset operates assuming this offset is equal during acquisition of each
  - If assumption holds,
    field can never change
  - Otherwise the estimated field will be erroneous

$$\Delta \hat{\omega}_{t} = \frac{\arg(e^{i\hat{\phi}_{t}}e^{-i\hat{\phi}_{t-1}})}{TE_{t} - TE_{t-1}}$$
$$\Delta \hat{\omega}_{t+1} = \frac{\arg(e^{i\hat{\phi}_{t+1}}e^{-i\hat{\phi}_{t}})}{TE_{t+1} - TE_{t}}$$

$$\Delta \hat{\omega}_t = \Delta \hat{\omega}_{t+1}$$

# Moving Racetrack Trajectory

- Modified EPI retracing multiple k-space lines at a constant  $\Delta TE$  within a single RF shot
- Red paths indicate the first pass and green the second acquisitions of the line
- Generally low resolution  $\Delta \hat{\omega}_{t} = \frac{\arg \left( e^{i\hat{\phi}_{,pass^{2}}} e^{-i\hat{\phi}_{,pass^{1}}} \right)}{nt_{esp}}$

<sup>1</sup>V Roopchansingh et al., MRM 50:839-843, 2003

 $\Delta \hat{\omega}_t$  = estimated frequency offset at time t  $\phi_{t, pass N}$  = estimated phase at time t for pass N  $t_{esp}$  = echo spacing time *t*=1,...,N-1

#### **Expected Accuracy**

- Image phase measurement includes N(0, $\sigma^2$ ) noise,  $\eta_1$ ,  $\eta_2$
- $\phi_{\rm e}$  represents all other phase errors
  - Change in  $\phi_0$  between images
  - Any response to variable accumulation, such as intraacquisition motion
  - Any difference in the field during acquisition of both images
- Difference between *TEs* is important as noise amplifies with decreasing difference

$$\Delta \hat{\omega} = \frac{\arg(e^{i(\phi_2 + \eta_2)}e^{-i(\phi_1 + \eta_1)}e^{i\phi_e})}{TE_2 - TE_1}$$

#### Methods

- Test performance of dual echo time EPI against MRTT, which is not susceptible to the same errors
- Two scans performed, one with phantom and the other human
  - MRTT acquired at full resolution
    - (all k-space acquired twice)
  - -TE also increased by 1.872ms on every other image

### Methods

- Scan parameters
  - $-64 \times 64$
  - 24cm FOV
  - S1. Thickness = 3.8cm
  - -TE = 44.3
  - -TR = 1
  - Flip angle = 45 degrees
  - Reps = 276;

\* $\Delta TE$  was equal in both scans to preserve equal SNR

- Phantom scanning (spherical agar phantom) involved no involvement beyond scanner operation
- A single time series in a single human subject was acquired. Subject was told only to lay still and rest
- After estimation of raw field maps, each was fit using a 7<sup>th</sup> order polynomial to reduce noise

#### Results



Average power spectrum of voxel time series in a 5×5 voxel region for phantom (left) and human (right). Results of Dual Echo Time EPI data shown in blue and MRTT in red.

• Both plots show elevated power in the dual *TE* case, even at specific frequencies in the phantom.

-Likely scanner instability or variable RF pulse phase.

• Human results are elevated across the whole spectrum, with the greatest difference at lower frequencies where expected physiologic response is likely being amplified.

#### Results

- Shows disparity between MRTT and dual TE maps
- Disparities more apparent & significant in human data
  - Suggests that violating the assumption of field equality has severe consequences



Maps of t-statistics from a paireddifference test between field maps estimated using MRTT and the dual echo time methods. Statistics for phantom maps shown left and human maps right

#### Discussion

- The dual echo technique produces different results than the MRTT, but correctness of either is uncertain
- Appropriateness of dynamic field correction
  - If correction may be error prone, must weigh cost to benefit
  - Most valuable for complex analysis
  - Newer, more robust techniques

# **Final Thought**

- The dual echo EPI method should still be robust for creating static estimations, especially when averaging
  - Probably the easiest technique to implement
- Acknowledgements:
  - This work was supported in part by NIH EB00215 and EB007827